

# Multi-physics Simulation of the Biomedical Process- Heart Electrophysiology

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# Research Plan

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## ○ Goal

- Utilize a set of computer programs to study and simulate the multi-physics phenomena of the heart.

## ○ Steps

- Study and understand the governing equations for simulating the heart: Monodomain Model and Beeler-Reuter Model.
- Develop the geometry and mesh of the heart.
- Program the electrical models: Beeler-Reuter and Monodomain model.
- Examine the interaction between the electrical and physiological effects of the heart.

# Phase 1: Bidomain and Monodomain Model (Tissue Model)

## Bidomain Model

$$\nabla \cdot (M_i \nabla v) + \nabla \cdot (M_i \nabla u_e) = \frac{\partial v}{\partial t} + I_{ion}(v, s)$$

After assumptions of homogeneity between the intracellular and extracellular components of the heart the model is simplified into Monodomain Model

$$\frac{\Lambda}{1 + \Lambda} \nabla \cdot (M_i \nabla v) = \frac{\partial v}{\partial t} + I_{ion}(v, s)$$

Using the operator splitting schemes, the Monodomain model can be split into a set of equations which can be solved simultaneously at different time steps

$$\begin{aligned} \frac{\partial v}{\partial t} &= -I_{ion}(v, s), & v(t_n) &= v^n \\ \frac{\partial s}{\partial t} &= f(v, s), & s(t_n) &= s^n \end{aligned}$$

The partial differential equation below can then be solved linearly at different time steps

$$\frac{\partial v}{\partial t} = \frac{\Lambda}{1 + \Lambda} \nabla \cdot (M_i \nabla v), \quad v(t_n) = v_\theta^n$$

# Beeler Reuter Model( Cellular Model)

## Potential and Current Equations

$$V^{n+1} = V^n + \frac{dV}{dt} \Delta t + O(\Delta t)^2$$

$$\frac{dV}{dt} = - \frac{(i_{k1} + i_{x1} + iNa + iCa - i_{external})}{Cm}$$

$$i_{k1} = \left\{ \frac{4\{\exp[0.04(V + 85)] - 1\}}{\exp[0.08(V + 53)] + \exp[0.04(V + 53)]} + \frac{0.2(V + 23)}{1 - \exp[-0.04(V + 23)]} \right\}$$

$$i_{x1} = x_1 \cdot 0.8 \cdot \frac{\{\exp[0.04(V + 77)] - 1\}}{\exp[0.04(V + 35)]}$$

$$iNa = (gNa \cdot m^3 \cdot h \cdot j + gNaCa)(V - ENa)$$

## Gates Equations (ODE)

$$\frac{dx_1}{dt} = \alpha_{x1}(1 - x_1) - \beta_{x1}x_1$$

$$\frac{dm_1}{dt} = \alpha_{m1}(1 - m_1) - \beta_{m1}m_1$$

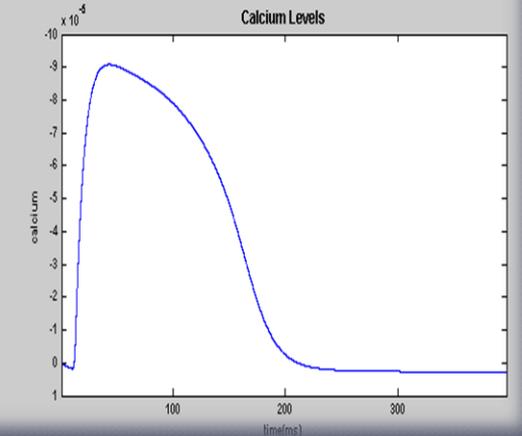
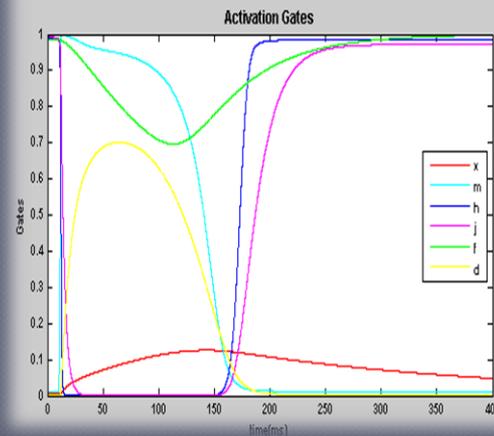
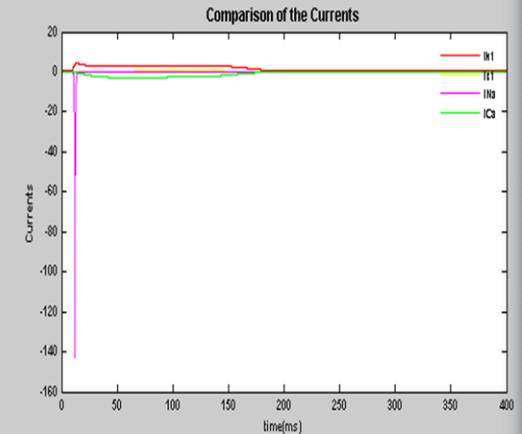
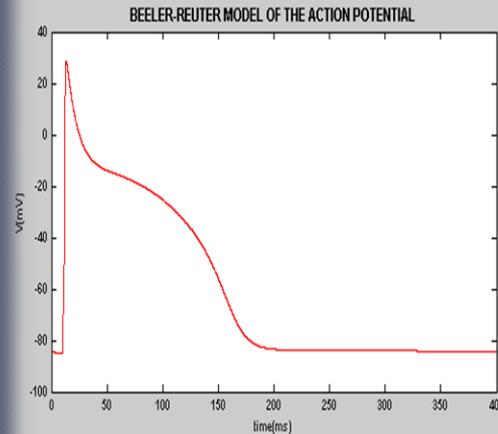
$$\frac{dh_1}{dt} = \alpha_{h1}(1 - h_1) - \beta_{h1}h_1$$

$$\frac{dj_1}{dt} = \alpha_{j1}(1 - j_1) - \beta_{j1}j_1$$

$$iCa = gCa \cdot d \cdot f \cdot (V - ECa)$$

$$\frac{dd_1}{dt} = \alpha_{d1}(1 - d_1) - \beta_{d1}d_1$$

$$\frac{df_1}{dt} = \alpha_{f1}(1 - f_1) - \beta_{f1}f_1$$



# Phase 2- CUBIT Meshing

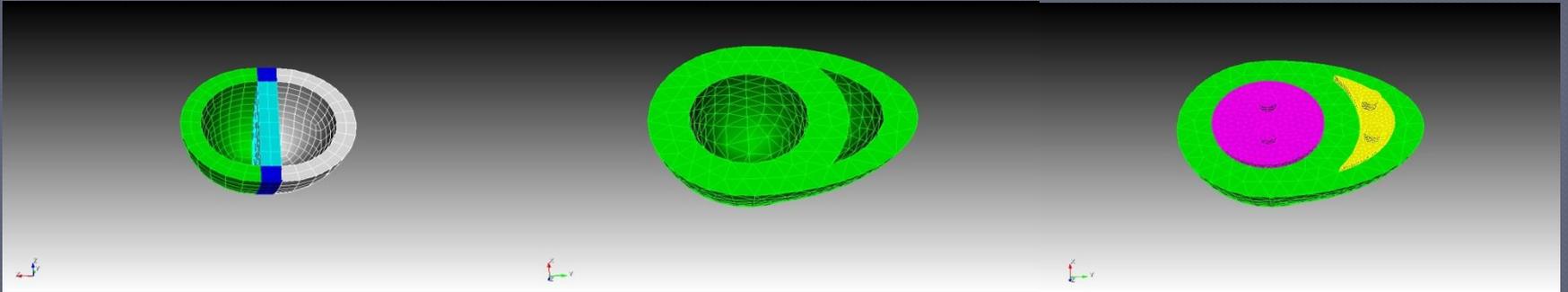
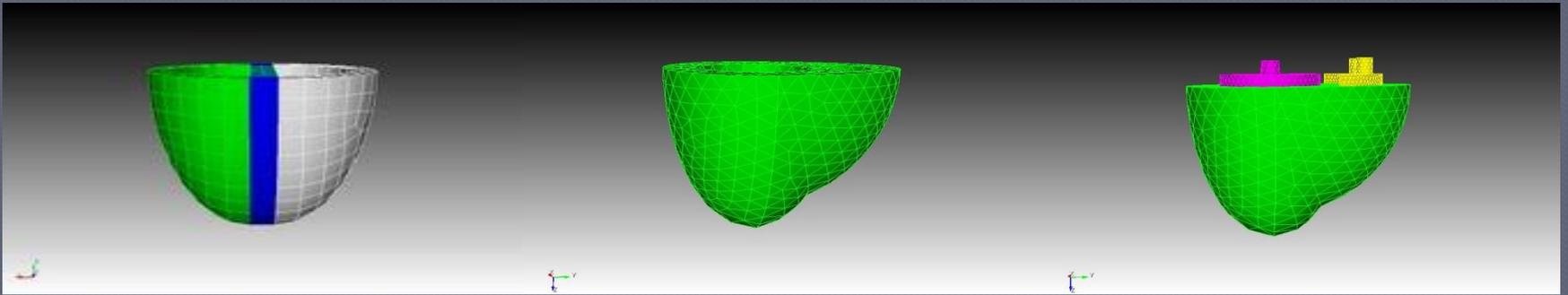


Figure 1

Figure 2

Figure 3

Models of the heart developed and meshed in CUBIT