

Parallel Discontinuous Galerkin Method

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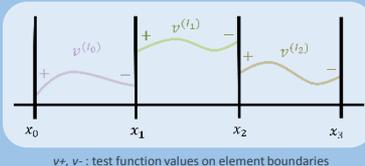
Overview

Discontinuous Galerkin Method (DG-FEM) is a class of Finite Element Method (FEM) for finding approximation solutions to systems of differential equations that can be used to simulate chemical transport phenomena.

The goal of my project is to implement parallelization on DG-FEM codes that can be scaled on existing supercomputers.

DG-FEM

In standard Finite Element Method, test functions are chosen for the weak formulation of the differential equation. DG-FEM chooses test functions that are discontinuous across adjacent elements, resulting jump conditions on the shared boundaries.



Mathematics behind

1D Poisson's Equation on domain $I = [a, b]$

$$\begin{cases} -u'' = f \\ u(a) = u(b) = 0 \end{cases}$$

Weak formulation using test function v

$$\begin{aligned} -\int_a^b u'' v &= -\sum_{j=0}^{N-1} \int_{x_j}^{x_{j+1}} u'' v \\ &= \sum_{j=0}^{N-1} \left(\int_{x_j}^{x_{j+1}} u' v' + u'(x_{j+1}^+) v(x_{j+1}^-) - u'(x_{j+1}^-) v(x_{j+1}^+) \right) \\ &= \sum_{j=0}^{N-1} \int_{x_j}^{x_{j+1}} u' v' + u'(x_j^+) v(x_j^+) + \left(-u'(x_j^-) v(x_j^-) + u'(x_j^-) v(x_j^+) \right) + \dots \\ &\quad + \left(-u'(x_{j+1}^-) v(x_{j+1}^-) + u'(x_{j+1}^-) v(x_{j+1}^+) \right) - u'(x_{j+1}^-) v(x_{j+1}^+) \\ &= \sum_{j=0}^{N-1} \int_{x_j}^{x_{j+1}} u' v' + u'(x_j^+) v(x_j^+) + \sum_{j=0}^{N-1} [u]_j v_j - u'(x_{j+1}^-) v(x_{j+1}^+) \end{aligned}$$

Jump conditions: $[u]_j = \{u\}_j^+ - \{u\}_j^- + [u]_j' [v]_j$
 $= \left(\frac{1}{2} (u'(x_j^+) + u'(x_j^-)) \right) (v(x_j^+) - v(x_j^-)) + |v(x_j^-)| \frac{1}{2} (u'(x_j^+) + u'(x_j^-))$

1D Linear System Construction

Bilinear Function for Stiffness Matrix:

$$a(u, v) \equiv \sum_{j=0}^{N-1} \int_{x_j}^{x_{j+1}} u' v' + \sum_{j=0}^{N-1} \left(\{u\}_j^+ [v]_j^+ + \frac{[u]_j' [v]_j^-}{2} \right) + \gamma \sum_{j=0}^{N-1} \frac{1}{|T_j|} [u]_j [v]_j$$

symmetric term penalty term

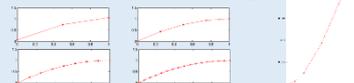
Basis Functions for u_j :



Solving Linear System:

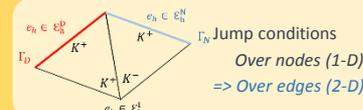
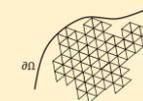
$$\sum_{j=1}^M a(\phi_j, \phi_i) \alpha_j = \int f \phi_i + \text{symmetric term} + \text{penalty term}$$

Decrease in error norm with cell size:



From 1D to 2D

Partition of Domain:
 Intervals (1-D)
 \Rightarrow Triangles (2-D)



2D DG-FEM: more complex code structure

Parallel Computing over Serial Computing

LAPACK / ScaLAPACK
 - Dense matrix solver only

DG-FEM Stiffness Matrix
 - Positive Definite - Sparse

Less time
 Less storage
 Larger problem

Trilinos
 - Compressed row storage
 - Also sparse matrix solver

1D Parallelization

Matrix Construction

Solving Linear System

Serial:
 Global Matrix

Serial: LAPACK

Parallel: ScaLAPACK

Parallel:
 Local Matrices

Serial:
 LAPACK on MPI

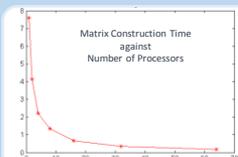
Parallel:
 Trilinos

Solver

Iterative

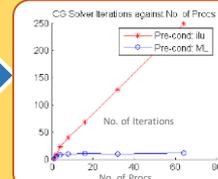
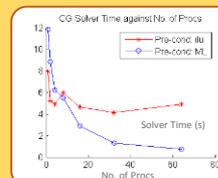
Preconditioner

ML Library



AztecOO on Trilinos

No. of Cells = 5,000,000
 No. of Procs = 1,2,4,8,16,32,64



CG Iterative Solver + ML Preconditioner
 = LESS solver time + STABLE no. of iter.

Why DG-FEM matters

Discontinuity between element boundaries provides local support and leads to:

- ✓ Local refinement
- ✓ Complex geometries
- ✓ Parallelization
- ✓ Higher-order accuracy

My Work

- ✓ Construct a 1-D DG-FEM serial code
- ✓ Construct a 1-D DG-FEM partial parallel code (LAPACK on MPI)
- ✓ Construct a 1-Dimension DG-FEM fully parallel code (Trilinos)
- ✓ Analyze parallelization performances

Future

- Extend the code to 2-D and 3-D DG-FEM fully parallel code
- Expand the code to be adaptive for local refinement, and cover chemical transport equations

Acknowledgement

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